



# Θεωρία δυναμό περιστρεφόμενων τυρβωδών ροών

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### Natural dynamos

The existence of planetary, stellar and galactic magnetic fields is attributed to the dynamo action



The mechanism by which a background turbulent flow spontaneously generates a magnetic field

# Why are magnetic fields important?

- Impact of solar wind on the planet's magnetosphere → magnetic storms
- Geomagnetic storms: observed as aurorae by the naked eye
- Magnetic storms can cause:
  - interruptions to radio communications and GPS
  - e disruption to power grids
  - damage to space-crafts
  - extinction of certain species that use magnetoception





Dynamo problem

$$\partial_t \mathbf{B} = \boldsymbol{\nabla} \times (\mathbf{u} \times \mathbf{B}) + \eta \boldsymbol{\nabla}^2 \mathbf{B}$$
$$\partial_t \mathbf{B} + \mathbf{u} \cdot \boldsymbol{\nabla} \mathbf{B} = \mathbf{B} \cdot \boldsymbol{\nabla} \mathbf{u} + \frac{1}{Rm} \boldsymbol{\nabla}^2 \mathbf{B}$$
$$\mathbf{h} = \frac{|\boldsymbol{\nabla} \times (\mathbf{u} \times \mathbf{B})|}{Rm} - \frac{|\mathbf{U}L|}{Rm} \mathbf{h}$$

• 
$$Rm = \frac{|\nabla \times (\mathbf{u} \times \mathbf{B})|}{|\eta \nabla^2 \mathbf{B}|} = UL/\eta$$

- ${\ensuremath{\bullet}}$  The induction equation is linear in  ${\ensuremath{\mathbf{B}}}$
- It admits solutions of the form  $\mathbf{B} = \mathbf{b}(m{x})\exp(\lambda t)$
- The induction equation becomes an eigenvalue problem with  $\lambda=\gamma+i\omega$
- $\bullet$  For a given  ${\bf u}$  we have the following solutions
  - $\gamma < 0$ : non-dynamo
  - $\gamma > 0$ : kinematic dynamo  $Rm_c$

# Anti-dynamo theorems

Cowling's Theorem (1934)

- Axisymmetric magnetic fields cannot be generated via dynamo action
- Field must be inherently 3D for  $\gamma > 0$

Zel'dovich Theorem (1957)

- Planar velocity fields (2D flow) are not capable of sustaining dynamo action
- ... All analytical and numerical calculations will have to be 3D

#### Laboratory dynamos

- Since 1960s several experimental groups try to reproduce the dynamo instability in the laboratory using liquid metals
- However, so far, unconstrained dynamos driven just by turbulent flows have not been achieved in the laboratory!!!
- Successful experimental dynamos rely either in constraining the flow (Riga and Karlsruhe) or using ferromagnetic materials (VKS).



# The challenge for liquid-metal dynamos

- Liquid Sodium at  $T=393\,K$   $\nu\sim 10^{-7}\,m^2/s,\,\eta\sim 10^{-1}\,m^2/s$
- Magnetic Prandtl number  $Pm = \nu/\eta = Rm/Re \ll 1$
- Kinetic Reynolds number  $Re = UL/\nu \gg 1$
- Energy injection rate  $\epsilon \propto Re^3$
- The dynamo onset is extremely costly to reach in the laboratory



Fauve & Lathrop, FluidDynAstoGeo (2005)

# Numerical dynamos

- Degrees of freedom in DNS 
  $$\begin{split} N &\equiv (L/\ell_d)^3 \propto R e^{9/4} \text{ with } \\ \ell_d \propto (\nu^3/\epsilon)^{1/4} \end{split}$$
- The value of  $Rm_c$  increases monotonically for values of  $Pm \sim 1$
- Turbulent fluctuations prevent the dynamo instability
- For high Re a finite value of  $Rm_c$  was reached independent of Re, i.e.  $Rm_c^{turb} \equiv \lim_{Re \to \infty} Rm_c$



# Turbulent dynamos

• Natural dynamos are highly turbulent and so inherently multi-scale



- $Pm \gg 1$ : no problem except that the field is generated on very small scales
- $Pm \ll 1$ : the magnetic field dissipates in the inertial range of the turbulence
- Note that it is harder to drive a dynamo with a rough velocity than with a smooth velocity

#### Rotation of planets & stars

Rotation determines the main characteristics of the resulting flows and magnetic fields of planets and stars





Courtesy by NASA



Courtesy by C. Garraffo (Harvard)

# Rotating MHD equations

$$\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} = -\frac{1}{\rho} \nabla P - 2\mathbf{\Omega} \times \mathbf{u} + \nu \nabla^2 \mathbf{u} + \mathbf{f}$$
$$\partial_t \mathbf{B} = \nabla \times (\mathbf{u} \times \mathbf{B}) + \eta \nabla^2 \mathbf{B}$$

- $\mathbf{\Omega} = \Omega \hat{\mathbf{e}}_z$
- Non-helical cellular flow at  $k_f L_{box} = 4$  $\mathbf{f} = f_0(\cos(k_f y), \sin(k_f x), \cos(k_f y) + \sin(k_f x))$
- The non-dimensional parameters  $Re = \frac{u}{k_f \nu}$ ,  $Rm = \frac{u}{k_f \eta}$ ,  $Ro = \frac{uk_f}{2\Omega}$ with  $u = (\epsilon/k_f)^{1/3}$  and  $\epsilon \equiv \langle \mathbf{u} \cdot \mathbf{f} \rangle$
- Power required for the dynamo onset  $\epsilon_c \propto (Rm_c^{turb})^3$ with  $Rm_c^{turb} \equiv \lim_{Re\to\infty} Rm_c$

We are interested in the following limits:

- $Re \gg 1$  limit (or  $Pm \ll 1$ ): we use hyperviscosity  $\nabla^8$  for  ${\bf u}$  only
- $Ro \ll 1$  limit: we use an asymptotic quasi-2D model

#### Fast rotating limit $Ro \ll 1$

In this limit,  $\mathbf{u}$  becomes invariant along the axis of rotation

$$\begin{split} \partial_t \mathbf{u}_{_{2D}} + \mathbf{u}_{_{2D}} \cdot \nabla \, \mathbf{u}_{_{2D}} &= -\nabla p + \nu \nabla^2 \mathbf{u}_{_{2D}} + \mathbf{f}_{_{2D}} \\ \partial_t u_z + \mathbf{u}_{_{2D}} \cdot \nabla \, u_z &= \nu \nabla^2 u_z + f_z \end{split}$$

with  $\mathbf{u}_{\scriptscriptstyle 2D} = \boldsymbol{\nabla} \times \boldsymbol{\psi} \hat{\mathbf{e}}_z.$ 

Due to the invariance of the flow along the z-direction  $\mathbf{B} = \mathbf{b}(x,y,t)e^{ik_z z}$ 

Each  $k_z$ -mode evolves independently and the induction equation reads

$$\partial_t \mathbf{b} + \mathbf{u}_{2D} \cdot \nabla \mathbf{b} + u_z i k_z \mathbf{b} = \mathbf{b} \cdot \nabla \mathbf{u}_{2D} + \eta \left( \Delta - k_z^2 \right) \mathbf{b}$$

The  $\nabla \cdot \mathbf{B} = 0$  for each magnetic mode gives

$$\partial_x b_x(x, y, t) + \partial_x b_y(x, y, t) = -ik_z b_z(x, y, t)$$

In this limit we follow only the  $k_z = 1$  mode that was found to be the most unstable mode (see Seshasayanan & Alexakis, JFM 2016)

# Rotating turbulent flows



# Three regimes





# Critical magnetic Reynolds number $Rm_c$

• To calculate  $Rm_c$  we run simulations of the same flow (same Re and Ro) for different values of Rm



- The growth rate of the magnetic field is computed as  $\gamma \equiv \lim_{t \to \infty} \frac{1}{2t} \log \frac{\langle |\mathbf{B}|^2(t) \rangle}{\langle |\mathbf{B}|^2(0) \rangle}$
- $Rm_c$  is determined by linear interpolation of the growth-rates between dynamo ( $\gamma > 0$ ) and non-dynamo ( $\gamma < 0$ ) runs

### $Rm_c$ as a function of Re for different $\Omega$



- $\Omega = 0$ : similar behaviour to other studies of non-rotating dynamos
- $\Omega = 1$ : initial hindering effect for the dynamo by rotation
- $\Omega \ge 3$ : much lower threshold for the dynamo instability
- $\Omega = 3$ : same threshold, implying that the destructive effect of the 3D turbulent fluctuations on dynamo has already disappeared

#### Power requirements



The ratio

 $\frac{Rm_c^{turb}|_{\Omega=0}}{Rm_c^{turb}|_{\Omega=3}}\sim 13$ 

• So, power consumption reduces by

$$\frac{\epsilon_c|_{\Omega=0}}{\epsilon_c|_{\Omega=3}} \sim 2 \cdot 10^3 \quad !!!$$

since  $\epsilon_c \propto (Rm_c^{turb})^3$  , with  $Rm_c^{turb} \equiv \lim_{Re \to \infty} Rm_c$ 

#### Practical considerations

Technical constrains limit:

- $\bullet\,$  the size of liquid metal laboratory experiments  $L\sim 2m$
- ${\rm \bullet}\,$  the magnetic diffusivity of liquid sodium  $\eta \simeq 10^{-1}\,{\rm m}^2/{\rm s}\,$
- $\bullet\,$  the density of liquid sodium  $\rho\simeq 10^3\,{\rm kg/m}^3$

Assuming  $Rm_c \simeq 50$ , energy consumption  $\epsilon > 100 \text{ kW}$ 

The VKS experiment consumed 300 kW at its peak.

This large  $\epsilon$  limits dynamo experiments to large industrial size laboratories

A reduction of  $Rm_c$  even by a factor of 2, reduces this consumption rate to  $\sim 10~{\rm kW}$ 

Such a reduction can make dynamos attainable in small scale laboratories!

# Kinetic energy spectra



- Large enstrophy implies a large stretching rate  $u_\ell/\ell$  of the magnetic field lines
- $\Omega = 0$ : close to Kolmogorov behaviour with  $E(k) \propto k^{-5/3}$  with the strongest stretching rate at the small incoherent scales
- $\Omega = 3$ :  $k^2 E(k)$  decreases with k. At the smallest scales the  $k^{1/3}$  starts to form again
  - small scale fluctuations are suppressed
  - the dominant stretching rate is restricted to the large scales

### Magnetic energy spectra

Magnetic energy spectra for Rm close to the onset



- $\Omega = 0$ : spectrum is almost flat with an exponential cut-off
- Ω = 3: spectrum decreases fast with k, and peaks at (k<sub>f</sub> = 3), while magnetic energy at k = 1 is an order of magnitude smaller

# Visualisations

Structures from an unstable eigenmode of the dynamo at  $\Omega = 3$ 

vertical vorticity field  $\pmb{\omega}_z$ 



vertical currect field  $j_z$ 



• The dynamo behaves as if it is driven by an organised laminar flow (i.e. high *Pm* behaviour) even at very large *Re* (i.e. at low values of *Pm*).

## Dynamo growth rate dependence on coherence time

- We compare dynamos with the same spectra but different coherence time
- We consider the flow with  $\Omega = 3$
- We randomise the phases of each Fourier coefficient at different coherence times  $\tau_c$
- $\hat{\mathbf{u}}_{new}(\mathbf{k}_{\perp}) = \hat{\mathbf{u}}(\mathbf{k}_{\perp}) \exp(i\phi_{k_{\perp}}),$   $\phi_{k_{\perp}}$ : random numbers  $k_{\perp} = \sqrt{k_x^2 + k_y^2}$
- $\tau_c/\Delta t = \infty$ : flow without randomised phases ( $\Box$ )
- $\tau_c/\Delta t = 1$ : flow with delta-correlation in time



#### Conclusions

- $Rm_c$  for a turbulent non-helical dynamo in the  $Pm \ll 1$  limit can be significantly reduced if the flow is submitted to global rotation
- Even for moderate rotation rates (i.e. Ro = 0.2) the required energy injection rate can be reduced by a factor of more than  $10^3$
- This suggests a new paradigm to realise liquid metal dynamo experiments in small-scale laboratories
- This strong decrease of  $Rm_c$  is due to
  - the suppression of turbulent fluctuations and
  - the spatio-temporal organisation of the large scales
- The dynamo growth rate is determined by the long-lived large scale coherent eddies